

$L_{\mathfrak{S}_1}$ - 不分明化邻近结构和滤子

蒋志勇

(华东交通大学 基础科学学院, 江西 南昌 330013)

摘要:本文基于连续值逻辑用语义方法定义了不分明化 δ -邻近结构和不分明化滤子,并由不分明化 δ -邻近结构给出了 δ -不分明化邻域系的概念;证明了这种定义下的 δ -不分明化邻域系构成不分明化滤子,得到了不分明化 δ -邻近结构的可分离性与 δ -不分明化邻域系 N_x 的 T_1 、 T_0 -可分离性的等价性。

关键词:不分明化 δ -邻近结构;不分明化滤子; δ -不分明化邻域系

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定义 1^[1] 设 X 是一个论域,称一元 F -谓词 $K \in \mathcal{A}(\mathcal{A}(X))$ 是 X 的一个不分明化滤子,若

$$(1) \models \phi \notin K \wedge K \neq \phi$$

$$(2) \models (\forall A, B)((A \in K) \wedge (B \in K) \rightarrow A \cap B \in K)$$

$$(3) \models (\forall A, B)((A \subseteq B) \wedge (A \in K) \rightarrow B \in K)$$

定义 2 设 X 是一个论域,称二元 F -谓词 $\delta \in \mathcal{A}(\mathcal{A}(X) \times \mathcal{A}(X))$ 是 X 上的一个不分明化 δ -邻近结构,若

$$(1) \models (A, B) \in \delta \rightarrow (B, A) \in \delta \quad \text{此处的“} \rightarrow \text{”实际上可以改成“} \leftrightarrow \text{”}$$

$$(2) \models (A \subseteq C) \wedge (B \subseteq D) \rightarrow ((A, B) \in \delta \rightarrow (C, D) \in \delta)$$

$$(3) \models \neg(\phi, X) \in \delta$$

$$(4) \models \neg(A \cap B = \phi) \rightarrow (A, B) \in \delta$$

$$(5) \models \neg(A, C) \in \delta \wedge \neg(B, C) \in \delta \rightarrow \neg(A \cup B, C) \in \delta$$

$$(6) \models \neg(A, B) \in \delta \rightarrow (\exists C \subseteq X)(\neg(A, C) \in \delta \wedge \neg(B, X - C) \in \delta)$$

定理 1 设 $\delta \in \mathcal{A}(\mathcal{A}(X) \times \mathcal{A}(X))$ 是 X 上的一个不分明化 δ -邻近结构,定义一元 F -谓词 $N_A \in \mathcal{A}(\mathcal{P}(X))$ ($\phi \neq A \subseteq X$) 如下: $B \in N_A := \neg(A, X - B) \in \delta$, $B \subseteq X$, 则 N_A (称为 A 的 δ -不分明化邻域系) 是 X 的一个不分明化滤子。

$$\text{证明: } (1) 0 \leq N_A(\phi) = 1 - \delta(A, X) \leq 1 - [\neg(A \cap X = \phi)] = 0 \Rightarrow [\neg(\phi \in N_A)] = 1$$

$$1 \geq N_A(X) = 1 - \delta(A, \phi) \geq 1 - \delta(\phi, A) \geq 1 - \delta(\phi, X) = 1 \Rightarrow N_A(X) = 1$$

$$(2) \inf_{B, C \subseteq X} \min(1, 1 - \min(N_A(B), N_A(C)) + N_A(B \cap C))$$

$$= \inf_{B, C \subseteq X} \min(1, 1 - \min(1 - \delta(A, X - B), 1 - \delta(A, X - C)) + 1 - \delta(A, X - B \cap C))$$

$$\geq \inf_{B, C \subseteq X} \min(1, 1 - \min(1 - \delta(X - B, A), 1 - \delta(X - C, A)) + 1 - \delta(A, X - B \cap C))$$

$$\geq \inf_{B, C \subseteq X} \min(1, 1 - (1 - \delta((X - B) \cup (X - C), A)) + 1 - \delta(A, X - B \cap C))$$

$$= \inf_{B, C \subseteq X} \min(1, \delta((X - B) \cup (X - C), A) + 1 - \delta(A, X - B \cap C))$$

$$= \inf_{B, C \subseteq X} \min(1, \delta(X - B \cap C, A) + 1 - \delta(A, X - B \cap C))$$

$$\geq \inf_{B, C \subseteq X} \min(1, \delta(A, X - B \cap C) + 1 - \delta(A, X - B \cap C)) = 1$$

$$(3) \inf_{B \subseteq C} \min(1, 1 - N_A(B) + N_A(C))$$

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作者简介:蒋志勇(1966-),男,江西南昌人,硕士,副教授,研究方向为模糊逻辑与模糊推理。

$$= \inf_{B \subseteq C} \min(1, 1 - (1 - \delta(A, X - B)) + (1 - \delta(A, X - C)))$$

$$= \inf_{B \subseteq C} \min(1, 1 + \delta(A, X - B) - \delta(A, X - C)) \geq 1$$

定理 2 设 $\delta \in \mathcal{A}(\mathcal{A}(X) \times \mathcal{A}(X))$ 是 X 上的一个不分明化 δ -邻近结构, 对于 $x \in A$, 定义 x 的 δ -不分明化邻域系 $N_x \in \mathcal{A}(\mathcal{A}(X))$ 为: $A \in N_x := \neg(\{x\}, X - A) \in \delta, A \subseteq X$. 则

(1) N_x 构成 X 的一个不分明化滤子. 特别地, 有 $\models (\forall x)(\forall A)(A \in N_x \rightarrow x \in A)$.

(2) $\models (\forall x \neq y)(\neg(\{x\}, \{y\}) \in \delta$

$$\leftrightarrow (\exists A)((A \in N_x) \wedge (y \notin A)) \wedge (\exists B)((B \in N_y) \wedge (x \notin B)))$$

(3) $\models (\forall x \neq y)(\neg(\{x\}, \{y\}) \in \delta$

$$\leftrightarrow (\exists A)((A \in N_x) \wedge (y \notin A)) \vee ((A \in N_y) \vee (x \notin A))).$$

证明: (1) 关于 N_x 构成 X 的不分明化滤子只要在定理 1 的证明当中取 $A = \{x\}$ 即可.

$$\because 1 \geq \inf_{x \notin A} \min(1, 1 - N_x(A)) = \inf_{x \notin A} \min(1, \delta(\{x\}, X - A))$$

$$\geq \inf_{x \notin A} \min(1, 1 - [\{x\} \cap (X - A) = \emptyset]) = 1$$

$$\therefore \inf_{x \notin A} \min(1, 1 - N_x(A)) = 1.$$

(2) 往证: $\inf_{x \neq y} (1 - \delta(\{x\}, \{y\})) = \inf_{x \neq y} \min(\sup_{A \subseteq X, y \notin A} N_x(A), \sup_{B \subseteq X, x \notin B} N_y(B))$

事实上, 一方面

$$\inf_{x \neq y} (1 - \delta(\{x\}, \{y\})) = \inf_{x \neq y} N_x(X - \{y\}) \leq \inf_{x \neq y} \sup_{A \subseteq X, y \notin A} N_x(A)$$

$$\inf_{x \neq y} (1 - \delta(\{x\}, \{y\})) = \inf_{x \neq y} N_y(X - \{x\}) \leq \inf_{x \neq y} \sup_{B \subseteq X, x \notin B} N_y(B)$$

从而

$$\inf_{x \neq y} (1 - \delta(\{x\}, \{y\})) \leq \inf_{x \neq y} \min(\sup_{A \subseteq X, y \notin A} N_x(A), \sup_{B \subseteq X, x \notin B} N_y(B))$$

另一方面, 设 $\inf_{x \neq y} \min(\sup_{A \subseteq X, y \notin A} N_x(A), \sup_{B \subseteq X, x \notin B} N_y(B)) > \alpha, 0 \leq \alpha < 1$

则对 $\forall x, y \in X, x \neq y, \exists A, B \subseteq X, y \notin A, x \notin B, N_x(A) > \alpha, N_y(B) > \alpha$

所以

$$N_x(X - \{y\}) = 1 - \delta(\{x\}, \{y\}) \geq 1 - \delta(\{x\}, X - A) = N_x(A) > \alpha$$

$$N_y(X - \{x\}) = 1 - \delta(\{x\}, \{y\}) \geq 1 - \delta(\{y\}, X - B) = N_y(B) > \alpha$$

从而

$$\inf_{x \neq y} (1 - \delta(\{x\}, \{y\})) \geq \inf_{x \neq y} \min(\sup_{A \subseteq X, y \notin A} N_x(A), \sup_{B \subseteq X, x \notin B} N_y(B))$$

综上所述

$$\inf_{x \neq y} (1 - \delta(\{x\}, \{y\})) = \inf_{x \neq y} \min(\sup_{A \subseteq X, y \notin A} N_x(A), \sup_{B \subseteq X, x \notin B} N_y(B)).$$

(3) 与(2)类似可证: $\inf_{x \neq y} (1 - \delta(\{x\}, \{y\})) = \inf_{x \neq y} \max(\sup_{A \subseteq X, y \notin A} N_x(A), \sup_{B \subseteq X, x \notin B} N_y(B)).$

注: 定理 2 的(2)和(3)实际上刻画了 X 上的不分明化 δ -邻近结构的可分离性与 $x(x \in X)$ 的 δ -不分明化邻域系 N_x 的 T_1 、 T_0 -可分离性是等价的。

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$L_{\mathfrak{S}_1}$ - Fuzzifying Proximity Structure and Filter

JIANG Zhi-yong

(School of Basic Sciences, East China Jiaotong University, Nanchang 330013, China)

Abstract: This article defines the fuzzifying δ -proximity structure and fuzzifying filter based on the continuous value logic with the semantic method, and gives the concept of the δ -fuzzifying neighborhood system by the fuzzifying δ -proximity structure. It proves the δ -fuzzifying neighborhood system is the fuzzifying filter, obtains the fuzzifying δ -proximity structure separability and T_1 、 T_0 - separability equivalence of the δ -fuzzifying neighborhood system.

Key words: fuzzifying δ -proximity structure; fuzzifying filter; δ -fuzzifying neighborhood system

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A Research on Comprehensive Evaluation for HOV Lane Based on Projection Pursuit

WANG Wei-li¹, YUAN Zhong-dan²

(1. School of Naval Architecture, Ocean & Civil Engineering, Shanghai Jiaotong University, Shanghai 201805; 2. School of Road and Traffic Engineering College, Tongji University, Shanghai 200092)

Abstract: As an important basis for practical application, the comprehensive evaluation for the results of HOV lanes is attracting more and more attention. To make objective, scientific and quantitative evaluation, based on the comprehensive evaluation system for HOV lanes and the principles of projection pursuit, the paper presents a new method, HOV lanes comprehensive evaluation. The paper forecasts and analyzes the result of HOV lanes to provide reference for the application of HOV Lanes in China.

Key words: HOV Lanes; projection pursuit; comprehensive evaluation

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